

For the following two questions, recall that we define a rigid motion to be a function  $\phi : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  of the form  $\phi = T_{\vec{v}} \circ R_A$  for some rotation  $R_A$  and translation  $T_{\vec{v}}$ .

1. Show that if  $\phi : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is of the form  $\phi = R_A \circ T_{\vec{v}}$ , where  $R_A$  is a rotation and  $T_{\vec{v}}$  is a translation, then  $\phi$  is a rigid motion.
2. Use the result of the previous problem to show that the composition of two rigid motions is a rigid motion. [Hint: for any two square matrices  $A$  and  $B$ ,  $\det(AB) = \det(A)\det(B)$ . Also, use the associativity of function composition.]
3. Recall from class that for  $M$  a metric space with metric  $d_M$  and  $x \in M$ , we defined a function  $d^x : M \rightarrow \mathbb{R}$  by  $d^x(y) = d_M(x, y)$ . Prove that  $d^x$  is continuous.
4. Prove that a surjective isometry is a homeomorphism. (NOTE: When I stated this result in class, I forgot to mention that this requires surjectivity.) [HINT: To establish continuity, you will need to deal directly with the rigorous definition of continuity.]
5. Prove that a subset  $S$  of a metric space is open if and only if it contains none of its boundary points.
6. Which of the following subsets  $S$  of  $\mathbb{R}^2$  are open?
  - $S = \{(1, 1)\}$ ,
  - $S =$  the  $x$ -axis,
  - $S = \{(x, y) \mid y - 1 < x < y + 1\}$ ,
  - $S = \{(x, y) \mid y - 1 < x \leq y + 1\}$ ,
  - $S = \{(x, y) \mid y - 1 \leq x \leq y + 1\}$ ,