AMAT 584 Lecture 10

Today: Cech complexes, Rips complexes.

Definition:

For $X = \{x_1, ..., x_n\} \subset IR^n$ and r > 0, the <u>Cech complex</u> Cech(X,r) is the abstract simplicial complex with vertex set $\{x_1, ..., x_n\}$, such that

[xjo, ..., xjk] & Čech(X,1) iff

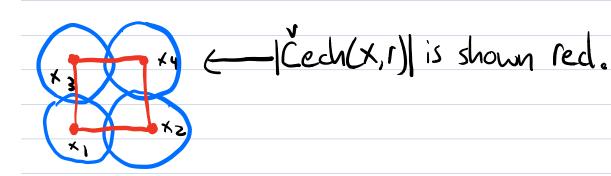
 $B(x_{j_0},r) \cap B(x_{j_1},r) \cap B(x_{j_k},r) \neq \phi$.

Example from last lecture:

Let r= z+ S, 5 small

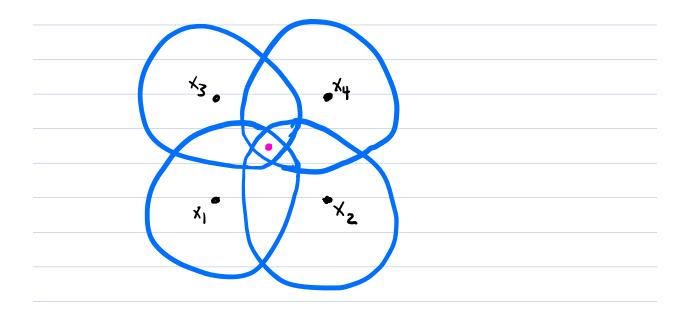
I've drawn B(xi.r) for each if {1,..,4}, in blue.

(ech(X,r)= {[x1],[x2],[x3], [x4],[x1,x2],[x1,x3],[x2,x4],[x3,x4]}



Note that |Cech(X,r)| is homotopy equivalent to U(X,r): U(X,r) deformation retracts onto |Cech(X,r)|

Now let Γ' be large enough so that the center point $(\frac{1}{2}, \frac{1}{2})$ is contained in each closed ball, i.e. $\Gamma' \geqslant \frac{12}{2}$.



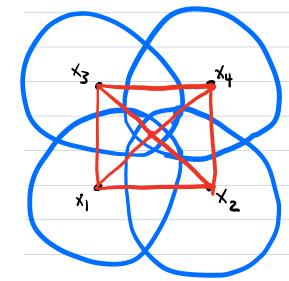
Cech(X, 1') contains all possible simplices on the vertex set {x,..., x4} i.e.,

Cech(X,11)=

{[x1],[x2],[x3], [x4],[x1,x2],[x1,x3],[x2,x4],[x3,x4],[x2,x3],[x,x4],[x2,x3],[x2,x3],[x2,x3],[x2,x3],[x2,x3],[x2,x3],[x3,x4],[

Definition: The k-skeleton of a simplicial complex is the subcomplex consisting of all simplices of dimension at most k.

Thus, the 1-skeleton of Cech(X, r') looks like this.



The 1-skeleton is the complete graph on 4 vertices, i.e., every pair of vertices is connected by an edge.

|(ech(x,r')) = |Geo(Cech(x,r')) is the 3-simplex

[e1,ez,e3,e4] in R4.
This is a tetrahedron.
A more intuitive way to think about (ech(x,r')) is this:-Start with 4 points. - Give in an edge between each pair of points - For each triple of points, give in a triangle. - Give in the solid tetrahedron.
(hollow) (filled in)
Note in particular that (ech(X,1') does not sit inside IR2, even though X sits inside IR2.
Remark: In general, if X is an (astract) simplicial complex with $ V(X) =k+l$, and X contains all non-empty subsets of $V(X)$, then $ X $ is a k-simplex.
Thus, in this case, we call X a k-simplex. Thus, in the context of simplicial complexes, "simplex" has several meanings, but they are all very closely related.

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Note that, as above I(ech(X,1')) and U(X,1') are
Note that, as above I(ech(X,r1) and U(X,r1) are homotopy equivalent: Both are h.e. to a point.
Theorem: For any finite X <ir' 1="" and="">0, U(X,r) ~ (ech(X,r). means "is homotopy equivalent to"</ir'>
The theorem is not that easy to prove. It is an immedition consequence of a more general result called the nerve theorem, which is very important in topology.
Exercise: .x3
X ₁ × ₂

Consider X={x1,..., >3} as above, and r so that the balls B(x1,1) intersect as shown.

What is (ech(X,r)? What is (ech(X,r))?